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Impacts of Tempo and Mode of Environmental Fluctuations on Population Growth: Slow- and Fast-Limit Approximations of Lyapunov Exponents for Periodic and Random Environments

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Abstract

Populations consist of individuals living in different states and experiencing temporally varying environmental conditions. Individuals may differ in their geographic location, stage of development (e.g., juvenile versus adult), or physiological state (infected or susceptible). Environmental conditions may vary due to abiotic (e.g. temperature) or biotic (e.g. resource availability) factors. As the survival, growth, and reproduction of individuals depend on their state and environmental conditions, environmental fluctuations often impact population growth. Here, we examine to what extent the tempo and mode of these fluctuations matter for population growth. We model population growth for a population with d individual states and experiencing N different environmental states. The models are switching, linear ordinary differential equations $x'(t) = A(\sigma(\omega t))x(t)$ where $x(t) = (x_1(t), \dots, x_d(t))$ corresponds to the population densities in the d individual states, $\sigma(t)$ is a piece-wise constant function representing the fluctuations in the environmental states $1, \ldots, N, \omega$ is the frequency of the environmental fluctuations, and $A(1), \ldots, A(n)$ are Metzler matrices representing the population dynamics in the environmental states $1, \ldots, N.\sigma(t)$ can either be a periodic function or correspond to a continuous-time Markov chain. Under suitable conditions, there exists a Lyapunov exponent $\Lambda(\omega)$ such that $\lim_{t\to\infty} \frac{1}{t} \log \sum_i x_i(t) = \Lambda(\omega)$ for all non-negative, non-zero initial conditions x(0) (with probability one in the random case). For both random and periodic switching, we derive analytical first-order and second-order approximations of $\Lambda(\omega)$ in the limits of slow ($\omega \to 0$) and fast ($\omega \to \infty$) environmental fluctuations. When the order of switching and the average switching times are equal, we show that the first-order approximations of $\Lambda(\omega)$ are equivalent in

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the slow-switching limit, but not in the fast-switching limit. Hence, the mode (random versus periodic) of switching matters for population growth. We illustrate our results with applications to a simple stage-structured model and a general spatially structured model. When dispersal rates are symmetric, the first-order approximations suggest that population growth rates decrease with the frequency of switching, which is consistent with earlier work on periodic switching. In the absence of dispersal symmetry, we demonstrate that $\Lambda(\omega)$ can be non-monotonic in ω . In conclusion, our results show that population growth rates often depend both on the tempo (ω) and the mode (random versus deterministic) of environmental fluctuations.

Keywords Lyapunov exponents \cdot Matrix models \cdot Stochastic and periodic switching \cdot Population growth

1 Introduction

Central to many questions in ecology, evolution, and epidemiology is the identification of how environmental conditions determine population growth. This growth depends on the survival, growth and reproduction of individuals, which in turn depends on the state of an individual (*i*-state). Individuals may differ in their *i*-state based on their geographic location, stage of development, genotype, or behavior (DeAngelis 2018). One way to account for these difference in *i*-state on the population state (*p*-state) is using Matrix Population Models (MPM) (Caswell 2001; DeAngelis 2018). In these models, there are a finite number d of i-states and the p-state corresponds to the vector, $x = (x_1, x_2, \dots, x_d)$, of population densities. For continuous-time MPMs, a matrix A with non-negative off diagonal elements, a_{ij} with $i \neq j$, define the rates at which individuals in state *j* contribute to individuals in different state *j*. These contributions may correspond to individual's transition to the other state (e.g., dispersing from one geographic location to another, developing from one stage to another, changing their behavior) or producing individuals of the other state. Diagonal elements, a_{ii} , of the matrix A can be positive, zero, or non-negative and correspond to the net rate at which individuals leave their current state (including death) and produce more individuals of the same state. Under constant environmental conditions, the continuous-time MPM is a linear system of differential equations

$$x'(t) = Ax(t) \tag{1}$$

where A, with its non-negative off-diagonal entries, is called a Metzler matrix (Mitkowski 2008). These continuous-time MPM commonly arise when linearizing a disease-free equilibrium for an epidemiological model, the extinction equilibrium of a demographic model, or a fixation equilibrium of a population genetics model (Bürger 2000; Hethcote 2000; Kon et al. 2004). When the matrix A is irreducible, the Perron-Frobenius Theorem implies that for any non-negative, non-zero initial condition x(0)

$$\lim_{t \to \infty} \frac{1}{t} \ln \sum_{i} x_i(t) = \lambda(A)$$
(2)

where $\lambda(A)$ is the spectral abscissa of *A* i.e. the maximum of the real parts of the eigenvalues of *A*. Hence, $\lambda(A)$ determines the long-term growth rate of the population. In particular, when $\lambda(A)$ is positive, the population persists and grows. When $\lambda(A)$ is negative, the population declines exponentially quickly to the extinction state.

Most populations experience fluctuations in environmental conditions such as temperature, precipitation, and nutrient availability. As these environmental conditions determine the survival, growth, and reproduction of individuals, environmental fluctuations lead to fluctuations in demographic rates. Understanding the implication of these fluctuations on population growth is an active topic (Tuljapurkar 1990; Boyce et al. 2006; Fay et al. 2020; Hilde et al. 2020; Kortessis et al. 2023b; Paniw et al. 2018; Schreiber 2023; Tuljapurkar and Haridas 2006). Almost all of this earlier work, see, however, Benaïm and Strickler (2019), Benaïm et al. (2023a) and Benaim et al. (2024), is for discrete-time MPMs. One of the simplest approaches to modeling this time-dependency in continuous-time MPMs is to allow A in (1) to switch between a finite number of Metzler matrices A_1, A_2, \ldots, A_N corresponding to N environmental states e.g. summer versus winter, wet versus dry period. If $\sigma(t)$ denotes the environmental state at time t, then we get a switched, continuous-time MPM

$$x'(t) = A_{\sigma(t)}x(t).$$

If $\sigma(t)$ is a periodic piecewise constant function or given by an irreducible Markov chain, then there exists the dominant Lyapunov exponent Λ such that

$$\Lambda = \lim_{t \to \infty} \frac{1}{t} \ln \sum_{i} x_{i}(t)$$
(3)

holds (with probability one in the random case) for any non-negative, non-zero initial condition x(0) (see Lemmas 1 and 2 below). As in the case of constant environment (1), the Lyapunov exponent measures the long-term population growth rate of the system. In particular, by a linearization procedure, it allows one to determine the persistence or extinction for switched non-linear flows (Benaïm and Strickler 2019).

Environmental fluctuations may occur at daily, yearly, and multidecadal time scales. This raises the question to what extent does the rate of switching between environmental states influence the population growth rate Λ ? To address this question, consider a fixed choice of Meltzer matrices A_1, \ldots, A_N and environmental trajectory $\sigma(t)$. To manipulate the rate of switching, let $\omega > 0$ be the frequency of environmental switching, in which case our MPM becomes

$$x'(t) = A_{\sigma(\omega t)} x(t).$$
(4)

Let $\Lambda(\omega)$ denote the dominant Lyapunov exponent (3) associated with the MPM with frequency ω . When switching is fast ($\omega \to \infty$), solutions of the switching model (4)

converge to the solution of an ODE $x' = \bar{A}x$ where the averaged matrix \bar{A} corresponds to the appropriate convex combination of the matrices A_i . In this limit, $\Lambda(\omega)$ converges to $\lambda(\bar{A})$ (Benaïm et al. 2014, 2023b; Benaim et al. 2024; Benaïm and Strickler 2019; Chitour et al. 2021; Du et al. 2021). In contrast, when the switching is slow ($\omega \rightarrow 0$), the Lyapunov exponent converges to a weighted average of the Lyapunov exponents $\lambda(A_i)$ of the matrices A_i (Benaïm et al. 2023b; Benaim et al. 2024). As the Lyapunov exponents of these limits are, in general, different, these earlier results imply that whether populations grow or decline can depend on the frequency of environmental switching.

These earlier results raise two interesting questions: Do the population growth rates increase or decrease as one approaches these limits? To what extent does the answer depend on whether the environmental switching is periodic or random? Whether periodic switching or random switching between some matrices yields the same behavior is a recurrent question in the study of switched linear systems. For example, Chitour et al. (2021) provides conditions on the matrices A_1, \ldots, A_N under which the maximal Lyapunov exponent obtained by considering the worst deterministic signal σ is strictly greater than the maximal probabilistic Lyapunov exponent obtained by considering the worst Markov chain. In particular, this shows that there exist matrices A_1, \ldots, A_N such that a suitable deterministic switching signal makes the system (4) unstable (the population persists), while it is stable for all Markovian signals (the population goes extinct). For applications in population dynamics, one is often interested either in the sign of the Lyapunov exponent (i.e. growth or extinction) or in its monotonicity with respect to some key parameters. For specific models, these questions can be answered in the fast- or slow-switching regimes with the explicit formula obtained in the present work. In particular, the monotonicity of the population growth in the switching rate is explicitly given in these two regimes by the sign of the first-order term in its expansion.

To address these questions, let $\Lambda_p(\omega)$ and $\Lambda_M(\omega)$ denote the Lyapunov exponents in the periodic case and the Markovian case, respectively. For fast Markovian (random) switching, Monmarché and Strickler (2023) answered one of these questions by deriving an asymptotic expansion of $\Lambda_M(\omega)$ in terms of $1/\omega$. Here, we address the remaining questions by deriving an asymptotic expansion of $\Lambda_p(\omega)$ in terms of $1/\omega$, and deriving first-order expansions in terms of ω of $\Lambda_p(\omega)$ and $\Lambda_M(\omega)$ is the slow-switching limit. For slow switching, we show that the periodic and random approximations of $\Lambda(\omega)$ are equivalent. However, in the limit of fast-switching, these approximations are not equivalent. In fact, when there is fast switching between two environments, we show that the first-order correction in terms of $\frac{1}{\omega}$ always vanishes and derive a second-order correction in terms of $\frac{1}{\omega^2}$. In contrast, the first-order term for Markovian switching is non-zero in general. We present these results in Sect. 3 after providing a more detailed description of the periodic and Markovian models in Sect. 2. To illustrate the applicability of our approximations, we apply them to a simple stage-structure model and explore their implications for spatially structure populations in Sect. 4. Consistent with previous work of Katriel (2022) for periodic environments, our approximations suggest that population growth rates increase with switching rates for spatially structured populations with symmetric dispersal. However, we use these approximations to illustrate how asymmetric dispersal can result in a non-monotonic relationship between switching frequency and population growth rates. Proofs of the main results are in Sects. 6 and 8.

2 Lyapunov Exponents of Periodic and Random Switching Models

Here, we provide more details about the switching continuous-time matrix population model in (4) and their Lyapunov exponents $\Lambda(\omega)$ in (3). For these models, $N \ge 1$ corresponds to the number of environmental states, $[\![1, N]\!] = \{1, 2, ..., N\}$ is the set of environmental states, and the demographic matrices $A_1, A_2, ..., A_N$ are $d \times d$ Metzler matrices i.e. have non-negative off-diagonal entries. We consider two approaches for specifying the piece-wise constant function $\sigma(t)$ that takes values $[\![1, N]\!]$. One approach is to assume that $\sigma(t)$ is a periodic, piecewise constant, right-continuous function. The other approach is to assume that $\sigma(t)$ corresponds to a continuous-time Markov chain on $[\![1, N]\!]$. These approaches are described in detail below.

The state space for the matrix population model is the non-negative cone $\mathbb{R}^d_+ = [0, \infty)^d$ of \mathbb{R}^d . If A_i is Metzler for all *i* in the model (4), then $x(0) \in \mathbb{R}^d_+$ implies that $x(t) \in \mathbb{R}^d_+$ for all $t \ge 0$ i.e. \mathbb{R}^d_+ is forward invariant for the dynamics.

For each form of the model, we also present results ensuring the existence of dominant Lyapunov exponent $\Lambda(\omega)$. To do this for the periodic case, let r(A) denote the spectral radius of A (i.e. the eigenvalue of A with the largest absolute value) and $\lambda(A)$ denote the spectral abscissa of A (i.e. the eigenvalue of A with largest real part). For a Metzler and irreducible matrix A, we can apply Perron-Frobenius Theorem to A + rI for some large enough r, to conclude that $\lambda(A)$ is a simple eigenvalue of A unique left eigenvector y with $\sum x_i y_i = 1$.

2.1 The Periodic Case

For the periodic version of the model (3), we assume that the function $\sigma : \mathbb{R} \to [\![1, N]\!]$ is piece-wise constant, right-continuous, has period 1 and successively takes the values $1, \ldots, N$ as follows

$$\sigma(t) = i$$
 for all $t \in [\tau_i, \tau_{i+1})$,

where $\tau_0 = 0$ and $\tau_{i+1} = \tau_i + \alpha_i$ for some $\alpha_i \ge 0$ satisfying $\sum_{i=1}^{N} \alpha_i = 1$. α_i represents the proportion of time spent in the environmental state *i* during a period of length $T := \omega^{-1}$.

Let $M(\omega)$ be the *monodromy matrix* associated with the model over the time interval [0, 1]:

$$M(\omega) = e^{\omega^{-1}\alpha_N A_N} \cdots e^{\omega^{-1}\alpha_1 A_1}$$

where e^M denotes the matrix exponential of the matrix M. For all initial conditions x(0) of (4), one can verify that $x(\omega^{-1}) = M(\omega)x(0)$. $M(\omega)$ is a matrix with nonnegative

entries, so that its principal eigenvalue $\lambda(M(\omega))$ is well defined. We have the following (see, e.g. (Benaïm et al. 2024, Thm. 2))

Lemma 1 If the matrices A_1, \ldots, A_N are Metzler and $\sum_{i=1}^N A_i$ is irreducible, then (3) holds for all non-zero initial conditions $x(0) \in \mathbb{R}^d_+$ and equals

$$\Lambda_p(\omega) = \omega \log \left(\lambda(M(\omega))\right).$$

2.2 The Markovian Case

For random environmental switching, let $\sigma(t)$ be a continuous-time Markov chain with transition rates $\xi_{ij} \ge 0$ from state *i* to state $j \ne i$. Let Ξ be the transition matrix with entries ξ_{ij} for $i \ne j$ and $\xi_{ii} = -\sum_{j \ne i} \xi_{ij}$. Assume Ξ is irreducible in which case there is a unique invariant probability measure $\alpha = (\alpha_1, \ldots, \alpha_N)$ in the environmental state space $[\![1, N]\!]$. Consider $(x(t), \sigma(\omega t))_{t \ge 0}$ where *x* solves (4). $(x(t), \sigma(\omega t))_{t \ge 0}$ is known as a Piecewise Deterministic Markov Process (PDMP).

For a non-negative, non-zero initial condition $x(0) \in \mathbb{R}^d_+$, decompose x(t) as $x(t) = \rho(t)\theta(t)$ where $\rho(t) = \mathbb{1} \cdot x(t) > 0$ with $\mathbb{1} = (1, ..., 1) \in \mathbb{R}^d$ and $\theta(t) = x(t)/\rho(t) \in \Delta = \{x \in \mathbb{R}^d_+, x_1 + \cdots + x_d = 1\}$. In this coordinate system, the switching model (4) is

$$\rho'(t) = (\mathbb{1} \cdot A_{\sigma(\omega t)}\theta(t))\rho(t), \qquad \theta'(t) = F_{\sigma(\omega t)}(\theta(t)) \tag{5}$$

with

$$F_i(\theta) = A_i \theta - (\mathbb{1} \cdot A_i \theta) \theta.$$
(6)

The following is proven in Benaïm et al. (2023b).

Lemma 2 Assuming that the matrices A_1, \ldots, A_N are Metzler and $\sum_{i=1}^N A_i$ is irreducible, then the Markov process $(\theta(t), \sigma(\omega t))_{t \ge 0}$ admits a unique invariant measure μ_{ω} on $\Delta \times [\![1, N]\!]$ and, moreover, the limit (3) exists almost surely, is deterministic, independent from the initial condition $x(0) \in \mathbb{R}^d_+ \setminus \{0\}$ and is given by

$$\Lambda_M(\omega) = \int_{\Delta \times [\![1,N]\!]} \mathbb{1} \cdot A_i \theta \, \mu_\omega(d\theta di). \tag{7}$$

3 General Results

Our most general results are first-order expansions of $\Lambda_p(\omega)$, $\Lambda_M(\omega)$ in terms of ω in the slow switching limit ($\omega \rightarrow 0$) and in terms of $\frac{1}{\omega}$ in the fast switching limit ($\omega \rightarrow \infty$). In the case of only two environments (N = 2), we show that the first-order correction term of $\Lambda_p(\omega)$ is zero in the fast switching limit, and derive a second-order approximation in terms of $\frac{1}{\omega^2}$. We also provide a simpler representation of the first-order approximation of $\Lambda_M(\omega)$ in the random case with two environments.

3.1 First Order Expansions of $\Lambda_p(\omega)$, $\Lambda_M(\omega)$ for Fast and Slow Switching

For the slow limit ($\omega \to 0$), we need the right eigenvectors x_i and the left eigenvectors y_i of A_i associated with the eigenvalue $\lambda(A_i)$. We assume that these eigenvectors are normalized so that $x_i^{\mathsf{T}} y_i = 1$ and $\mathbb{1}_d^{\mathsf{T}} x_i = 1$ where $\mathbb{1}_d$ is the column vectors with all entries equal to 1. For the fast limit ($\omega \to \infty$), define the average matrix

$$\bar{A} = \sum_{i=1}^{N} \alpha_i A_i$$

with weights $\alpha = (\alpha_1, ..., \alpha_N)$ given by $\alpha_i = \tau_{i+1} - \tau_i$ in the periodic settings of Sect. 2.1, or by the invariant measure of σ in the Markovian settings of Sect. 2.2. Let \bar{x} and \bar{y} the right and left eigenvectors of \bar{A} associated with the eigenvalue $\lambda(\bar{A})$ such that $\bar{x}^{\mathsf{T}}\bar{y} = 1$ and $\mathbb{1}_d^{\mathsf{T}}\bar{x} = 1$.

To state our main results, recall that the *matrix commutator* of two $d \times d$ matrix A and B is

$$[A, B] = AB - BA.$$

Furthermore, we need a generalized inverse for non-invertible matrices.

Definition 1 Let M be a matrix of index 1, which means that M and M^2 have the same rank. Then, *group inverse* of M is the unique solution X to the matrix equation

$$MXM = M, \quad XMX = X, \quad XM = MX.$$

When it is well defined, we denote the group inverse of M by M^{-1} .

Importantly for us, if *A* is an irreducible Metzler matrix, then $M = A - \lambda(A)I$ is an index 1, singular matrix. One way of computing M^{-1} is to use its rank factorization. Specifically, if *M* has rank k < d, then there is a $d \times k$ matrix *C* with rank *k* and a $k \times d$ matrix *F* with rank *k* such that M = CF. Then $M^{-1} = C(FC)^{-2}F$. There are multiple ways to obtain the ranking factorization. For example, if $M = U\begin{pmatrix} \Sigma_k & 0 \\ 0 & 0 \end{pmatrix}V$ is a singular value decomposition of *M* where Σ_k is a $k \times k$ diagonal matrix with the non-zero singular values of *M*, then one can choose *C* to be the first *k* columns of *U* and *F* to be the matrix product of Σ_k and the first *k* rows of *V*.

The following theorem provides first-order expansions of the Lyapunov exponents Λ_p , Λ_M in the slow and fast limits.

Theorem 1 Let A_1, \ldots, A_N be Metzler matrices such that \overline{A} is irreducible.

1. (Slow periodic switching) If A_1, \ldots, A_N are irreducible, then

$$\Lambda_p(\omega) = \sum_{i=1}^N \alpha_i \lambda(A_i) + c_{sp}\omega + \mathop{o}_{\omega \to 0}(\omega)$$
(8)

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with

$$c_{sp} = \sum_{i=1}^{N} \ln (x_i^{\mathsf{T}} y_{i+1})$$
 where $y_{N+1} = y_1$.

2. (Fast periodic switching)

$$\Lambda_p(\omega) = \lambda\left(\bar{A}\right) + c_{fp}\omega^{-1} + \mathop{o}_{\omega \to \infty}(\omega^{-1}) \tag{9}$$

with

$$c_{fp} = \bar{y}^{\mathsf{T}} \left(\frac{1}{2} \sum_{1 \le i < j \le N} \alpha_j \alpha_i [A_j, A_i] \right) \bar{x}$$

For the random switching case, assume, without loss of generality that, $\max_j \sum_{i \neq j} \xi_{i,j} = 1$, and define Q to be the jump matrix given by $q_{i,j} = \xi_{i,j}$ for $i \neq j$ and $q_{i,i} = 1 - \sum_{j \neq i} q_{i,j}$. Then

3. (Slow Markovian switching) If A_1, \ldots, A_N are irreducible, then

$$\Lambda_M(\omega) = \sum_{i=1}^N \alpha_i \lambda(A_i) + c_{sM}\omega + \mathop{o}_{\omega \to 0}(\omega)$$
(10)

with

$$c_{sM} = \sum_{i,j=1}^{N} \alpha_i q_{ij} \ln(y_j^{\mathsf{T}} x_i)$$

4. (Fast Markovian switching)

$$\Lambda_M(\omega) = \lambda\left(\bar{A}\right) + c_{fM}\omega^{-1} + \mathop{o}_{\omega \to \infty}(\omega^{-1}) \tag{11}$$

with

$$c_{fM} = \bar{y}^{\mathsf{T}} \left(\sum_{i,j} \alpha_i (Q - I)_{i,j}^{-1} A_j (\bar{x} \bar{y}^{\mathsf{T}} - I) A_i \right) \bar{x}.$$

The fast Markovian case (11) follows from (Monmarché and Strickler 2023, Proposition 2). The proofs for the other three cases are given in Sect. 6.

Remark The signs of the first-order terms suggest whether the Lyapunov exponents should be increasing or decreasing in the slow and fast switching limits. To ensure the monotonicity of Λ_p or Λ_M , it is necessary to prove that these functions are C^1 close

to 0 and ∞ . However, this proof is beyond the scope of the paper, even though we believe it is true, based on similar regular results existing in the literature (see, e.g. (Ruelle 1979, Theorem 3.1) or (Arnold et al. 1994, Corollary 4.11)) and numerical simulations.

Correspondence between periodic and random cases. For the slow switching case, there is a strong correspondence between the periodic and random approximations, as we now show. Let α_i be given for the periodic version of the model (see Sect. 2.1). The natural, random counterpart of this deterministic model follows the environmental states in the same order and, on average, remains in each environmental state for the same amount of time. To this end, let $\beta = \min_i \alpha_i$ and define the transition matrix Ξ by $\xi_{i,i+1} = \beta/\alpha_i$ for $1 \le i \le N - 1$, $\xi_{N,1} = \beta/\alpha_N$ and all other off-diagonal coefficients are 0. This transition matrix is such that the Markov process σ visits successively the states $1, \ldots, N$, its unique invariant probability measure is $\alpha = (\alpha_1, \ldots, \alpha_N)$, and $\max_i \sum_{j \ne i} \xi_{i,j} = 1$. The average time for σ to visit the *N* successive states (corresponding to one period of the deterministic signal) is $1/\beta$. Therefore, $\Lambda_M(\omega)$ should be compared with $\Lambda_p(\beta\omega)$. The asymptotic expansion (10) for the slow switching rate reads

$$\Lambda_{M}(\omega) = \sum_{i=1}^{N} \alpha_{i} \lambda(A_{i}) + \omega \sum_{i,j} \alpha_{i} q_{i,j} \ln(y_{j}^{\mathsf{T}} x_{i}) + \underset{\omega \to 0}{o}(\omega)$$

$$= \sum_{i=1}^{N} \alpha_{i} \lambda(A_{i}) + \omega \beta \sum_{i=1}^{N} \ln(y_{j}^{\mathsf{T}} x_{i}) + \underset{\omega \to 0}{o}(\omega),$$
(12)

which is exactly the formula of $\Lambda_p(\beta\omega)$ in the periodic case (8). This correspondence does not occur in the fast switching regime. Indeed, even when N = 2, Propositions 1 and 2 in the next section provide examples where the periodic and Markovian cases differ at first order.

The problem with reducible A_i in the slow limit. In Theorem 1, the slow switching formulae are proven under the additional assumption that each A_i is irreducible. To see why this assumption is necessary, we provide an example involving three reducible 2×2 matrices such that $\lim_{\omega \to 0} \Lambda_p(\omega) \neq \sum_i \alpha_i \lambda(A_i)$. That is, expansion (8) can fail at the zeroth order for reducible matrices. Consider the three, reducible matrices

$$A_1 = \begin{pmatrix} 2 & 1 \\ 0 & 1 \end{pmatrix}, \quad A_2 = \begin{pmatrix} 1 & 0 \\ 0 & 2 \end{pmatrix}, \text{ and } A_3 = \begin{pmatrix} 2 & 0 \\ 1 & 1 \end{pmatrix}$$

with $\lambda(A_1) = \lambda(A_2) = \lambda(A_3) = 2$. Let $\alpha_1 = \alpha_2 = \alpha_3 = 1/3$. The matrix $\overline{A} = \frac{1}{3} \sum_i A_i$ is irreducible. Writing $T = \omega^{-1}$, one can compute

$$\prod_{i=1}^{3} e^{A_i T/3} = e^T \begin{pmatrix} e^{2T/3} & (e^{T/3} - 1) e^{T/3} \\ (e^{T/3} - 1) e^{T/3} & (e^{T/3} - 1)^2 + e^{T/3} \end{pmatrix}$$

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whose dominant eigenvalue is

$$\frac{\sqrt{\left(2e^{\frac{5T}{3}} - e^{\frac{4T}{3}} + e^{T}\right)^{2} - 4e^{3T}}}{2} + e^{\frac{5T}{3}} - \frac{e^{\frac{4T}{3}}}{2} + \frac{e^{T}}{2} = 2e^{5T/3} + O(e^{-T/3}).$$

It follows that

$$\lim_{\omega \to 0} \Lambda_p(\omega) = \frac{5}{3} < 2 = \frac{1}{3} \sum_i \lambda(A_i).$$
(13)

3.2 Fast Switching with Two Matrices

In this section, we investigate the case when switching only between two matrices. In the periodic case, we show that the first-order term of the expansion is always 0, and give a second-order expansion.

Proposition 1 In the fast periodic case of Theorem 1, consider the case N = 2. Then, $c_{fp} = 0$. Moreover, for any Metzler matrices A_1 , A_2 of size $d \times d$,

$$\Lambda_p(\omega) = \lambda(\bar{A}) + c_{fp,2}\omega^{-2} + \mathop{o}_{\omega \to \infty}(\omega^{-2})$$
(14)

with

$$c_{fp,2} = \bar{y}^{\mathsf{T}} \Big(\frac{1}{12} \left[\alpha_2 A_2 - \alpha_1 A_1, \left[\alpha_2 A_2, \alpha_1 A_1 \right] \right] \\ + \frac{1}{4} \alpha_1^2 \alpha_2^2 [A_2, A_1] \left(\bar{A} - \lambda(\bar{A})I \right)^{-1} [A_2, A_1] \Big) \bar{x}$$

Proof First, we show that the first-order term is zero. By (9), this term is given by $c_{fp} = \frac{1}{2}\bar{y}^{\mathsf{T}}[\alpha_2 A_2, \alpha_1 A_1]\bar{x}$. Set $\bar{\lambda} = \lambda(\bar{A})$. By the definition of \bar{x} and \bar{y} , one has

$$\alpha_2 A_2 \bar{x} = (\bar{\lambda} - \alpha_1 A_1) \bar{x}$$
 and $\bar{y}^{\mathsf{T}} \alpha_2 A_2 = \bar{y}^{\mathsf{T}} (\bar{\lambda} - \alpha_1 A_1).$

Thus,

$$\bar{y}^{\mathsf{T}}[\alpha_2 A_2, \alpha_1 A_1]\bar{x} = \bar{y}^{\mathsf{T}} \alpha_2 A_2 \alpha_1 A_1 \bar{x} - \bar{y}^{\mathsf{T}} \alpha_1 A_1 \alpha_2 A_2 \bar{x}$$
$$= \bar{y}^{\mathsf{T}} (\bar{\lambda} - \alpha_1 A_1) \alpha_1 A_1 \bar{x} - \bar{y}^{\mathsf{T}} \alpha_1 A_1 (\bar{\lambda} - \alpha_1 A_1) \bar{x} = 0,$$

and $c_{fp} = 0$. Using the Baker-Campbell-Hausdorff formula (Rossmann 2006), we have $M(T) = \exp(TB(T))$, with

$$B(T) = \bar{A} + \frac{T}{2} [\alpha_2 A_2, \alpha_1 A_1] + \frac{T^2}{12} [\alpha_2 A_2 - \alpha_1 A_1, [\alpha_2 A_2, \alpha_1 A_1]] + o(T^2).$$

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By Theorem 4.1 in Haviv et al. (1992), we have for a matrix F and T small enough (recall that $\overline{\lambda}I - \overline{A}$ admits a group inverse)

$$\lambda(\bar{A} + TF) = \lambda(\bar{A}) + T\bar{y}^{\mathsf{T}}F\bar{x} + T^{2}\bar{y}^{\mathsf{T}}F(\bar{\lambda}I - \bar{A})^{-1}F\bar{x} + o(T^{2}).$$

Thus,

$$\Lambda_{p}(T^{-1}) = \bar{\lambda} + T \bar{y}^{\mathsf{T}} \left(\frac{1}{2} [\alpha_{2}A_{2}, \alpha_{1}A_{1}] + \frac{T}{12} [\alpha_{2}A_{2} - \alpha_{1}A_{1}, [\alpha_{2}A_{2}, \alpha_{1}A_{1}]] \right) \bar{x} + T^{2} \bar{y}^{\mathsf{T}} \frac{1}{4} \alpha_{1}^{2} \alpha_{2}^{2} [A_{2}, A_{1}] (\bar{\lambda}I - \bar{A})^{-1} [A_{2}, A_{1}] \bar{x} + o(T^{2}),$$

which gives the announced result.

We now provide a simpler formula for the first order term in (11) in the Markov switching case. In this case, the transition matrix is of the form

$$Q = \begin{pmatrix} 1 - p & p \\ 1 - p & p \end{pmatrix},\tag{15}$$

where $p = \xi_{1,2} \in (0, 1)$.

Proposition 2 In the fast Markov case of Theorem 1, consider case N = 2, with a transition matrix given by (15). Then, for any Metzler matrices A_1 , A_2 of size $d \times d$, (11) holds with

$$c_{fM} = p(1-p) \left[\bar{y}^{\mathsf{T}} (A_1 - A_2)^2 \bar{x} - \left(\bar{y}^{\mathsf{T}} (A_1 - A_2) \bar{x} \right)^2 \right].$$
(16)

In particular, if $A_1 - A_2$ is a diagonal matrix with entries $(\gamma_i)_{1 \le i \le d}$ on the diagonal, then

$$c_{fM} = (1-p)p\left[\sum_{i} \gamma_i^2 \bar{x}_i \bar{y}_i - \left(\sum_{i} \gamma_i \bar{x}_i \bar{y}_i\right)^2\right] \ge 0,$$

with strict inequality as soon as the γ_i are not all the same.

In particular, when switching randomly between two matrices, the first-order term in the fast regime expansion is, in general, not zero, contrary to the periodic switching case.

Proof The invariant measure of Q is $\alpha = (1 - p, p)$, and it is easily verified that $(Q - I)^{-1} = (Q - I)$. Hence, (11) reads

$$c_{fM} = (1-p)p\bar{y}^{\mathsf{T}} \left(A_1 P A_2 + A_2 P A_1 - A_1 P A_1 - A_2 P A_2\right)\bar{x},$$

with $P = I - \bar{x}\bar{y}^{\mathsf{T}}$. Straightforward computations lead to Eq. (16). Finally, since $\sum_i \bar{x}_i \bar{y}_i = 1$, the fact that $c_{fM} \ge 0$ in the case where $A_1 - A_2$ is diagonal follows from Jensen's inequality (alternatively from the Cauchy-Schwartz inequality).

4 Applications

4.1 Simple Stage-Structured Models

To illustrate the use of these approximations, we examine a stage-structured model with juveniles (x_1) and adults (x_2) . Juveniles mature to adults at a rate 1. We consider two versions of the model: one with fluctuating birth rates and one with fluctuating mortality rates. For both versions, there are two environments and the environment transitions between its states at a rate 1 when $\omega = 1$. Hence, the transition probabilities

of the jump process is $Q = \begin{pmatrix} 0.5 & 0.5 \\ 0.5 & 0.5 \end{pmatrix}$.

For the model with fluctuating birth rates, adults die at rate 1, reproduce at rate a > 0 in environment 1, and reproduce at rate b > 0 in environment 2. Assume that a > b, that is, the birth rate is higher in the environment 1. Hence,

$$A_1 = \begin{pmatrix} -1 & a \\ 1 & -1 \end{pmatrix} \text{ and } A_2 = \begin{pmatrix} -1 & b \\ 1 & -1 \end{pmatrix}.$$
(17)

In the slow switching limit ($\omega \rightarrow 0$), we get the approximation

$$\Lambda(\omega) = \bar{\lambda}_s + c_s \omega + o(\omega^2)$$

where

$$\bar{\lambda}_s = \frac{\sqrt{a}}{2} + \frac{\sqrt{b}}{2} - 1 \text{ and } c_s = \log\left(\frac{\left(\sqrt{a} + \sqrt{b}\right)^2}{4\sqrt{ab}}\right).$$

The zero-th order term $\overline{\lambda}_s$ corresponds to the average $\frac{1}{2}\sum_i \lambda(A_i)$ and is positive if $\sqrt{a} + \sqrt{b} > 2$. In particular, one needs a > 1 to ensure that individuals have a chance of replacing themselves in their lifetime. The second-order term equals zero if a = b and is positive otherwise. Hence, provided there is variation in birth rates, the population growth rate increases with frequency ω (at low frequencies).

In fast randomly switching environments ($\omega \rightarrow \infty$),

$$\Lambda_M(\omega) = \lambda(\bar{A}) + c_{fM} \frac{1}{\omega} + o\left(\frac{1}{\omega^2}\right)$$

The zero-th order term equals

$$\lambda(\bar{A}) = \frac{\sqrt{2(a+b)}}{2} - 1$$

and is positive only if the average birth rate $\frac{a+b}{2}$ is greater than one. Moreover, as we have $\lambda(\bar{A}) > \bar{\lambda}_s$, the long-term population growth rate is higher in the fast limit



Fig. 1 In A and B, the Lyapunov exponents for the juvenile-adult models (17) and (18), respectively, as functions of the switching frequency ω . Solid lines correspond to numerically approximated Lyapunov exponents for periodic (blue) and random (dashed red) switching. The dark grey dashed lines correspond to the analytical approximations. Parameters: In A, per-capita birth rates are a = 2.5 in environment 1 and b = 0.01 in environment 2. In B, the per-capita birth rate is a = 100 in both environments, the per-capita death rates for juveniles and adults are b = 40 and 1, respectively, in environment 1, and the per-capita death rates are 1 and b = 40, respectively, in environment 2 (Color figure online)

 $\omega \to \infty$ than in the slow limit $\omega \to 0$. The first-order correction term is

$$c_{fM} = -\frac{(a-b)^2}{8a+8b}.$$

This term is negative whenever there is variation in birth rates. In fast switching periodic environments ($\omega \rightarrow \infty$),

$$\Lambda_p(\omega) = \lambda(\bar{A}) + c_{fp,2}\frac{1}{\omega^2} + o\left(\frac{1}{\omega^3}\right)$$

where the second-order term equals

$$c_{fp,2} = -\frac{7\sqrt{2}(a-b)^2}{384\sqrt{a+b}}$$

This term is also negative whenever there is variation in birth rates.

Together, these approximations suggest that (i) the long-term population growth rate $\Lambda(\omega)$ increases with frequency ω and (ii) the long-term population growth rate is higher in the periodic environment than in the random environment. To explore what happens at intermediate frequencies, we numerically calculated $\Lambda_p(\omega)$ for a = 2.5(good times) and b = 0.01 (bad times) (Fig. 1A). For these birth rates, $\Lambda(0) < 0$ and $\lim_{\omega \to \infty} \Lambda(\omega) > 0$. As predicted by the approximations, the long-term population growth rate is increasing with ω and is always lower for the random environment. Interestingly, at intermediate frequencies (around $\omega \approx 0.5$), the long-term population growth rate is positive for a periodic environment but negative for the random environment. Hence, at these intermediate frequencies, populations persist in periodically switching environments, but not randomly switching environments. For the model with fluctuating death rates, adults have a per-capita birth rate of a. In environment 1, adults have a per-capita death rate of b and juveniles have a per-capita death rate of 1. In environment 2, juveniles have a per-capita death rate b, while adults have a per-capita death rate 1. Hence,

$$A_1 = \begin{pmatrix} -1 & a \\ 1 & -b \end{pmatrix} \text{ and } A_2 = \begin{pmatrix} -b & a \\ 1 & -1 \end{pmatrix}$$
(18)

We assume b > 1 i.e. environment 1 is worse for adults, while environment 2 is worse for juveniles.

In the slow switching limit ($\omega \rightarrow 0$), we get the approximation

$$\Lambda(\omega) = \bar{\lambda}_s + c_s \omega + o(\omega^2)$$

where

$$\bar{\lambda}_s = -\frac{b}{2} + \frac{\sqrt{4a+b^2-2b+1}}{2} - \frac{1}{2} \text{ and } c_s = \log\left(\frac{4a}{4a+(b-1)^2}\right)$$

The zero-th order term $\overline{\lambda}_s$ corresponds to the average $\frac{1}{2}\sum_i \lambda(A_i)$ and is positive if the birth rate *a* is greater than the maximal per-capita death rate b > 1. Under our assumption b > 1, the first-order term is negative. Hence, at lower frequencies, the population growth rate decreases with frequency.

Alternatively, in fast randomly switching environments ($\omega \rightarrow \infty$),

$$\Lambda_M(\omega) = \lambda(\bar{A}) + c_{fM} \frac{1}{\omega} + o\left(\frac{1}{\omega^2}\right)$$

The zero-th order term

$$\lambda(\bar{A}) = \sqrt{a} - \frac{b}{2} - \frac{1}{2}$$

is positive only if the square root of the average birth rate \sqrt{a} is greater than the average death rate $\frac{b+1}{2}$. Moreover, since we have $\lambda(\bar{A}) < \bar{\lambda}_s$, the long-term population growth rate is lower in the fast limit $\omega \to \infty$ than in the slow limit $\omega \to 0$. The first-order correction term for the fast, randomly switching environment

$$c_{fM} = \frac{(b-1)^2}{4}$$

is always positive. In fast, periodically switching environments ($\omega \rightarrow \infty$),

$$\Lambda_p(\omega) = \lambda(\bar{A}) + c_{fp,2} \frac{1}{\omega^2} + o\left(\frac{1}{\omega^3}\right)$$
(19)

where the second-order term

$$c_{fp,2} = \frac{7\sqrt{a}\,(b-1)^2}{96}$$

is also positive.

Together, these approximations suggest that (i) the long-term population growth rate $\Lambda(\omega)$ decreases with frequency ω and (ii) the long-term population growth rate is lower in the periodic environment than in the random environment. To explore what happens at intermediate frequencies, we numerically calculated $\Lambda_p(\omega)$ for a = 100 and b = 40 (Fig. 1B). For these birth-and-death rates, $\Lambda(0) > 0$ and $\lim_{\omega \to \infty} \Lambda(\omega) < 0$. As predicted by the approximations, the long-term population growth rate is decreasing with ω and is always higher for the random environment. Hence, at intermediate frequencies (around $\omega \approx 2$), the long-term population growth rate is positive for a random environment but negative for the periodic environment.

4.2 Metapopulation Models

To model the effects of spatial heterogeneity and environmental fluctuations on population growth, we consider a metapopulation occupying *d* distinct patches, i.e. a population of *d* populations coupled by dispersal (Hanski 1999). The population density in patch *i* is x_i with a per-capita growth rate of $r^i_{\sigma(\omega t)}$ at time *t*. Individuals from patch *j* disperse to patch *i* at rate $l_{i,j}$. The population dynamics in patch *i* are

$$x'_{i}(t) = r^{i}_{\sigma(\omega t)} x_{i} + \sum_{j \neq i} l_{i,j} (x_{j} - x_{i}).$$
⁽²⁰⁾

In matrix form, the metapopulation dynamics are

$$x'(t) = \underbrace{\left(R_{\sigma(\omega t)} + L\right)}_{=:A_{\sigma(\omega t)}} x(t).$$
(21)

where R_{σ} is a diagonal matrix with entries $r_{\sigma}^1, \ldots, r_{\sigma}^d$ and *L* is the dispersal matrix with entries $l_{i,j}$.

For a symmetric dispersal matrix and continuous (rather than piecewise continuous), periodic $r^i : \mathbb{R} \to \mathbb{R}$, Katriel (2022) proved the following result about monotonicity of $\Lambda_p(\omega)$ using results of Liu et al. (2022).

Theorem 2 (Katriel 2022) Assume L is irreducible and symmetric, $r^i : \mathbb{R} \to \mathbb{R}$ are continuous, period 1 functions that are not all equal. Then the dominant Floquet multiplier $\Lambda_p(\omega)$ of

$$x'_i(t) = r^i(\omega t) + \sum_{j \neq i} l_{i,j}(x_j - x_i).$$

is a strictly decreasing function of ω .



Fig. 2 The Lyapunov exponents and density-dependent dynamics for a two patch metapopulation model (21). In A, the Lyapunov exponent as a function of the switching frequency ω . Solid lines correspond to numerically approximated Lyapunov exponents for periodic (blue) and random (dashed red) switching. The dark gray, dashed lines correspond to the analytical approximations. Random (in C) and periodic (in C) simulations at frequency $\omega = 0.1$ for a nonlinear model whose linearization at the origin is given by (21). Parameters: $L = \begin{pmatrix} -0.1 & 0.1 \\ 0.1 & -0.1 \end{pmatrix}$, $R_1 = \begin{pmatrix} 0.5 & 0 \\ 0 & -1.5 \end{pmatrix}$, and $R_2 = \begin{pmatrix} -1.5 & 0 \\ 0 & 0.5 \end{pmatrix}$. For B and C, the dynamics are $x'(t) = A_{\sigma(\omega t)}x(t) - 0.01x(t) \circ x(t)$ (Color figure online)

Theorem 2 suggests that slower switching promotes metapopulation persistence, that is, a higher growth rate $\Lambda_p(\omega)$. In particular, if $\sum_{i=1}^{N} \alpha_i \lambda(A_i) > 0 > \lambda(\sum_{i=1}^{N} \alpha_i A_i)$, then there is a critical frequency ω^* such that the metapopulation persists if and only if the frequency ω of environmental switching lies below ω^* (see the blue curve in Fig. 2)

The following theorem shows that the behavior of $\Lambda(\omega)$ for small and large frequencies is consistent with what we would expect if Theorem 2 were to extend to random and periodic, piecewise continuous switching, and partially to asymmetric dispersal matrices *L*.

Theorem 3 Assume L is irreducible and R_i in (21) are not equal.

- 1. (Fast switching) $c_{fM} > c_{fp} = 0$.
- 2. (Slow switching) If L is symmetric or d = 2, then $c_{sp} \le 0$ and $c_{sM} \le 0$. Moreover, equality holds if and only if the right eigenvectors x_i of $A_i = R_i + L$ are all equal.

In the case of random switching, Theorem 3 suggests that sufficiently fast switching always reduces population growth rates. This occurs for all forms of dispersal, symmetric or asymmetric. If dispersal is symmetric or there are only two patches, Theorem 3 suggests that $\omega \mapsto \Lambda_M(\omega)$ decreases for sufficiently slow frequencies. Hence, we make the following conjecture for the random case:

Conjecture 1 Assume *L* is irreducible and the eigenvectors x_i of $A_i = R_i + L$ in (21) are not equal. If *L* is symmetric or d = 2, then $\omega \mapsto \Lambda_M(\omega)$ is strictly decreasing.



Fig. 3 The plain arrows represent the population migration, the dotted arrows the random transitions of the signal, i.e. of the state where there is a non-zero growth rate. Left: $\Xi = L^{T}$, the signal moves in the same direction as the population. Right: $\Xi = L$, the signal moves in the reverse direction (color figure)

Figure 2 illustrates Theorems 2 and 3 and Conjecture 1 numerically for a two-patch, two environment model (d = N = 2). For both random and periodic switching, the population growth rate $\Lambda(\omega)$ decreases with the switching frequency. Hence, the critical frequency ω^* below which the metapopulation persists is higher for the randomly switching environment than for the periodically switching environment.

What happens when there are $d \ge 3$ patches and the dispersal matrix L is asymmetric? It turns out that c_{sM} and c_{sp} can be positive and, consequently, $\omega \to \Lambda(\omega)$ need not be monotonic. To illustrate this possibility, consider patches lying along a circle and individuals moving clockwise along this circle. Specifically, let L be the cyclic permutation matrix:

$$L = \begin{pmatrix} -1 & 0 & \dots & 0 & 1 \\ 1 & -1 & \dots & 0 & 0 \\ 0 & 1 & \ddots & 0 & 0 \\ \vdots & \ddots & \ddots & \vdots & \vdots \\ 0 & 0 & \dots & 1 & -1 \end{pmatrix}$$

Namely $L_{i,i} = 1$, $L_{1,d} = 1$, $L_{i+1,i} = 1$ for $1 \le i \le d-1$, and $L_{i,j} = 0$ otherwise. We assume that there are N = d environmental states and that the growth per-capita of patch *i* in environmental state *i* equals $\rho + \beta \in \mathbb{R}$ and otherwise is $\rho \in \mathbb{R}$. That is, $r_i^i = \beta + \rho$ and $r_i^j = \rho$ for $i \ne j$. Finally, we consider the Markovian signal σ with the transition matrix Ξ being *L* or L^{\intercal} . When $\Xi = L^{\intercal}$, the signal moves in the same direction as the population (we call this the synchronized case), when $\Xi = L$ it goes backward (we call this the asynchronized case), see Fig. 3. As discussed at the end of Sect. 3.1, the first-order term expansion of $\Lambda_p(\omega)$ when σ deterministically goes from *i* to *i* + 1 (synchronized case) or from *i* to *i* - 1 (asynchronized) is given by $c_{sp} = dc_{sM}$.



Fig. 4 The Lyapunov exponent $\Lambda_p(\omega)$ from the circular metapopulation model with d = 3 patches. In panel A, the asynchronous case where $\Xi = L$. In panel B, the synchronous case where $\Xi = L^{T}$. The per-capita growth r_i^j in patch *i* equals -0.7 in environment j = i and 0.3 otherwise (Color figure online)

Proposition 3 Let η be the unique positive solution of $(\eta - \beta)\eta^{d-1} = 1$.

1. (synchronized case) If $\Xi = L^{\mathsf{T}}$, then

$$c_{sM} = c_{sM}^{sync} := \ln\left(\frac{(d-2)(\eta-\beta) + 2\eta}{(d-1)(\eta-\beta)\eta + \eta^2}\right).$$

In the case d = 3, the sign of c_{sM} is the opposite of the sign of β . For d > 3, its sign is the sign of $\beta_d - \beta$ where $\beta_d = \eta_* - \eta_*^{1-d} > 0$ with $\eta_* > 2(d-1)/(d+1) > 1$ the unique root of $X^{d+1} - 2X^d + (d-1)X - d + 2$ over $(1, \infty)$.

2. (asynchronized case) If $\Xi = L$, then

$$c_{sM} = c_{sM}^{async} := \ln\left(\frac{d\eta}{d-1+\eta^d}\right),$$

which is negative for all $\beta \neq 0$, $d \ge 3$.

For the periodic case where σ deterministically goes from *i* to *i* + 1 (synchronized case) or from *i* to *i* - 1 (asynchronized case), the first order term expansion of $\Lambda_p(\omega)$ is given by $c_{sp} = dc_{sM}$.

The proof of Proposition 3 is in Sect. 8. Figure 4 illustrates the main conclusions of this proposition with d = 3 patches, $\beta = -1$, and $\rho = 0.3$.

5 Discussion

Populations experience environmental fluctuations on multiple time scales, from diurnal cycles to multidecadal climate cycles (Hasegawa et al. 2022; Gorenstein et al. 2023). Here, we derived analytical approximations for how the frequency of these environmental fluctuations influences the long-term growth rate of structured populations. In the limit of low-frequency fluctuations, we derived new analytic approximations of the form $\Lambda(\omega) = \sum_i \alpha_i \lambda(A_i) + c\omega + o(\omega)$ with explicit formulas for *c* in periodic and random cases. In this low-frequency limit, we show that the mode of fluctuations, random versus periodic, has no effect on the population growth rate, that is, the correction terms c_p and c_M are equivalent when the random and periodic signal are comparable. This differs sharply from the high-frequency limit. In the limit of high-frequency fluctuations, we derived an analytical approximation for periodic environments that complements the work of Monmarché and Strickler (2023) for random environments. For both approximations, the population growth rate in the infinitely fast switching limit are equal (i.e. $\lim_{\omega \to \infty} \Lambda_p(\omega) = \lim_{\omega \to \infty} \Lambda_M(\omega) = \lambda(\sum_i \alpha_i A_i)$), but the firstorder correction terms with respect to the period $1/\omega$ of fluctuations, in general, differ (i.e. $c_{fp} \neq c_{fM}$). Indeed, for switching between two environments, the first-order correction term is zero for the periodic case, but (in general) non-zero for the random case. This difference implies that whether populations persist or not may depend on the mode of environmental switching.

5.1 Biological Interpretations of the Slow and Fast Limits

The slow limit approximation has a clear biological interpretation in terms of stablestate distributions x_i and vectors of reproductive values y_i – two fundamental quantities of population modeling (Caswell 2001). When environmental changes are rare, the distribution of the population approaches the stable state distribution of the current environment, say x_i in environment *i*. The reproductive values for this environment, the components of y_i , correspond to the contributions of an individual in each state to the long-term population (Caswell 2001). This interpretation of the absolute, rather than relative, contributions to the growth rate relies on the vector of reproductive values being normalized, so that the expected value of the reproductive value of a randomly chosen individual from the stable state distribution is one i.e. $y_i^T x_i = 1$ (Caswell 2001). When the environment shifts to a new environment, say j, the expected reproductive value of a randomly chosen individual shifts to $y_i^T x_i$ i.e. the expected reproductive value in the new environment of a randomly chosen individual from the old environment. When this new expectation is greater than one, individuals, on average, have greater reproductive value immediately after the environmental change. This increase in reproductive value increases the population growth rate by $\log(y_i^T x_i)$. If environmental changes, on average, boost reproductive values, then the long-term population growth rate $\Lambda(\omega)$ increases with frequency ω - at least for ω sufficiently low. This phenomenon is illustrated with our model (17) of a population of juveniles and adults where birth rates fluctuate between low and high values. In low birth rate environments, the stable state distribution mostly consists of adults and adults have slightly higher reproductive values. In high birth rate environments, there are mostly juveniles in the stable state distribution but adults have much high reproductive value. Hence, rare shifts from low birth rate to high birth rate environments substantially increase the average reproductive value of an individual. In contrast, rare shifts from high birth rate to low birth rate environments slightly decrease the average reproductive value of an individual. Hence, the net effect of environmental changes is positive and the long-term population growth rate $\Lambda(\omega)$ increases with frequency. In contrast, when the juvenile and adult death rates fluctuate, that is, Eq. (18), we get the opposite trend. In an environment with higher adult mortality, there are more juveniles at stable state distribution and juveniles have higher reproductive value. In an environment with higher juvenile adult mortality, adults are more common at the stable state distribution and adults have higher reproductive value. Hence, switching between environments always results in a decrease in the average reproductive value of an individual and a corresponding decrease in the population growth rate. Similar reasoning applies to the two patch metapopulation model in Fig.2: switching always results in more individuals in the lower quality patch and a reduction in the population growth rate.

The interpretation of the fast limit approximations is less clear in general. However, we can draw some conclusions in the case of random switching between two environments. When only the contribution of one population state to another population state fluctuates (i.e. a non-diagonal entry of A), Proposition 2 implies that higher frequency fluctuations always increase the long-term population growth rate. In contrast, when only the contribution of population states to themselves rapidly fluctuates (i.e. only diagonal terms fluctuate), higher frequencies decrease the long-term population growth rate. In particular, this conclusion applies to metapopulations with constant dispersal rates whose per-capita growth rates fluctuate between two values.

5.2 Implications for Metapopulations

For metapopulations with symmetric dispersal matrices, Katriel (2022) showed that the long-term population growth rate $\Lambda_p(\omega)$ always decreases with frequency when the per-capita growth rates exhibit periodic, continuous fluctuations. Hence, metapopulations exhibiting diffusive-like movement grow faster in low frequency, periodic environments. Here, we show that the same conclusion holds for randomly fluctuating environments in the limits of fast and slow switching (see Theorem 3). Moreover, in the fast switching limit, long-term population growth rates are higher in randomly switching environments than in periodically switching environments. An open problem (see Conjecture 1) is whether these conclusions hold at intermediate frequencies of random switching. However, when metapopulations exhibit asymmetric dispersal, we show that the long-term population growth rate may not vary monotonically with the environmental frequency ω . For example, we constructed an example (see Fig. 4) in which $\Lambda(\omega)$ is maximized at intermediate environmental frequencies. A likely hard open problem is characterizing which asymmetric dispersal matrices result in similar behaviors.

5.3 Relationship to Stochastic Demography

The effect of temporal variation in environmental conditions on the growth rate of the structured population is a main focus of the field of stochastic demography (Tuljapurkar 1990; Caswell 2001; Boyce et al. 2006; Hastings and Gross 2012). However, this extensive body of work focuses exclusively on discrete-time models. Hence, to make comparisons to this literature requires defining an appropriate metric of variation of instantaneous demographic rates, say an entry $a(\omega t)$ of the matrix $A_{\sigma(\omega t)}$. One natural



Fig. 5 Demographic variances (22) and (23) for the stage structured models (17)–(18) with fluctuating birth rates (A) and death rates (B). Parameters are as in Fig. 1 (color figure)

option is to consider the variation in the average demographic rate at stationarity over a fixed time interval, say of length one. In a random environment with stationary distribution π , this metric of variation equals

$$\operatorname{Var}_{M}(\omega) = \mathbb{E}_{\pi} \left[\left(\int_{0}^{1} a(\omega t) dt \right)^{2} \right] - \mathbb{E}_{\pi} \left[\int_{0}^{1} a(\omega t) dt \right]^{2}$$
$$= \mathbb{E}_{\pi} \left[\left(\frac{1}{\omega} \int_{0}^{\omega} a(t) dt \right)^{2} \right] - \mathbb{E}_{\pi} \left[\frac{1}{\omega} \int_{0}^{\omega} a(t) dt \right]^{2}$$
(22)

where \mathbb{E}_{π} corresponds to the expectation with $\mathbb{P}[\sigma(0) = i] = \pi_i$. Var_M(ω) is a smooth function of ω and converges to zero as $\omega \to 0$ (see, e.g., Monmarché and Strickler 2023). Similarly, one can define variation of a in the periodic environment as

$$\operatorname{Var}_{p}(\omega) = \int_{0}^{1} \left[\left(\frac{1}{\omega} \int_{0}^{\omega} a(s+t) dt \right)^{2} \right] ds - \left[\int_{0}^{1} \frac{1}{\omega} \int_{0}^{\omega} a(t+s) dt ds \right]^{2}$$
(23)

where a(t) is started randomly in the interval [0, 1]. $\operatorname{Var}_p(\omega)$ also converges to zero as $\omega \to \infty$. However, unlike the random case, this convergence is not monotone, as $\operatorname{Var}_p(\omega)$ equals zero at integer values. However, as illustrated in Fig. 5, the average birth-and-death rates for the juvenile-adult models tend to decrease with frequency for the periodic case and continuously decrease for random fluctuations. These trends facilitate comparisons with the stochastic demography literature.

A central dogma of stochastic demography is (Hastings and Gross 2012, page 96) "temporal variation in vital rates will typically lead to a reduction in population growth rate." This genesis of this dogma were discrete-time geometric random walks and the observation that the geometric mean is less than the arithmetic mean (Lewontin and Cohen 1969). For random discrete-time matrix models

x(t + 1) = A(t + 1)x(t), Tuljapurkar (1990) extended this dogma provided that non-negative matrices $A(1), A(2), \ldots$ are serially uncorrelated: the dominant Lyapunov exponent of this random product decreases with variation in the matrix entries. However, the continuous-time models considered here are inherently temporally autocorrelated over sufficiently short time scales. Consistent with our results, the central dogma of stochastic demography does not apply, in general, to discrete-time models with temporal autocorrelations: temporally autocorrelated fluctuations can increase population growth (Tuljapurkar 1990). This "inflationary effect" of autocorrelated fluctuations has been observed in stage-structured (Tuljapurkar and Haridas 2006) and spatially structured models (Roy et al. 2005; Tuljapurkar and Haridas 2006; Schreiber 2010; Kortessis et al. 2023a; Schreiber 2023). Consistent with these earlier studies, we found fluctuations in mortality for stage-structured models and per-capita growth rates in spatially structured models can generate this inflationary effect: lower frequencies of fluctuations generate greater variation in demographic rates averaged over a time step and higher population growth rates. Notably, our approximations suggest that this inflationary effect in spatially-structured population models occurs whenever there is symmetric dispersal.

5.4 Concluding Remarks

Our approach of modeling environmental fluctuations as a piecewise constant continuous process offers an analytically more tractable method for assessing the impact of environmental variability on the long-term growth rates of structured populations. The analytical approximations we have developed for growth rates in the limits of slow and fast environmental switching may serve as valuable new tools for theoretical biologists and applied mathematicians. These tools enable a deeper examination of how both the tempo (slow versus fast) and the mode (periodic versus random) of environmental fluctuations influence critical population dynamics, including growth, persistence, and risk of extinction. This refined approach not only enhances our understanding of population responses to environmental variability but also opens new avenues for research in population biology and applied mathematics with potential applications to epidemiology, ecology, population genetics, and conservation biology.

6 Proof of Theorem 1

6.1 Slow Periodic Switching

We prove formula (8). Recall that $T = \omega^{-1}$. We write $r_i = \mu(A_i)$. By Perron-Frobenius Theorem, for all *i*, for all T > 0,

$$e^{-r_i\alpha_i T}e^{\alpha_i T A_i} = p_i + o(e^{-\gamma T}),$$

where $\gamma > 0$ and $p_i = x_i y_i^{\mathsf{T}}$ is the projection matrix on x_i in the direction of y_i . Thus,

$$\prod_{i=1}^N e^{-r_i\alpha_i T} e^{T\alpha_i A_i} = \prod_{i=1}^N p_i + o(e^{-\gamma T}),$$

which leads to

$$\lambda(M(T)) = \prod_{i=1}^{N} e^{r_i \alpha_i T} \lambda\left(\prod_{i=1}^{N} p_i + o(e^{-\gamma T})\right)$$

Now, $\lambda \left(\prod_{i=1}^{N} p_i + o(e^{-\gamma T}) \right) = \lambda \left(\prod_{i=1}^{N} p_i \right) + o(\frac{1}{T})$ and

$$\prod_{i=1}^{N} p_i = x_N y_N^{\mathsf{T}} \dots x_1 y_1^{\mathsf{T}} = \left(\prod_{i=1}^{N-1} x_i^{\mathsf{T}} y_{i+1}\right) x_N y_1^{\mathsf{T}}.$$

In particular, $\lambda(\prod_{i=1}^{N} p_i) = \prod_{i=1}^{N-1} x_i^{\mathsf{T}} y_{i+1} \lambda(x_N y_1^{\mathsf{T}})$, where $x_N y_1^{\mathsf{T}}$ is the projection matrix on x_N in the direction of y_1^{T} . Hence, $\lambda(x_N y_1^{\mathsf{T}}) = x_N^{\mathsf{T}} y_1$. This concludes the proof by Lemma 1.

6.2 Fast Periodic Switching

This section is devoted to the proof of Formula (9). On the one hand, for an irreducible Metzler matrix B, we have

$$\lambda(e^B) = e^{\lambda(B)}.$$

Indeed, since *B* is Metzler and irreducible, e^B is a nonnegative irreducible matrix, hence $\lambda(e^B) = r(e^B)$. Now it is easily seen that $r(e^B) = e^{\lambda(B)}$ because the spectrum of e^B is the exponential of the spectrum of *B*. On the other hand, by an iteration of the Baker-Campbell-Hausdorff formula (Rossmann 2006), one has

$$M(T) = \exp\left(T\bar{A} + \frac{T^2}{2}\sum_{1 \le i < j \le N} [\alpha_j A_j, \alpha_i A_i] + o(T^2)\right)$$

Thus,

$$\frac{1}{T}\log\lambda(M(T)) = \lambda(B(T)), \qquad (24)$$

where $B(T) = \bar{A} + \frac{T}{2} \sum_{1 \le i < j \le N} \alpha_j \alpha_i [A_j, A_i] + o(T)$. Now, since \bar{A} has a unique dominant eigenvalue, the same holds for B(T), for T small enough. Moreover, one has $B'(0) = \frac{1}{2} \sum_{1 \le i < j \le N} \alpha_j \alpha_i [A_j, A_i]$. Thus, by (Horn and Johnson

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2013, Theorem 6.3.12) or (Haviv et al. 1992, Theorem 4.1), the function $T \mapsto \lambda(B(T))$ is differentiable at 0 and its derivative at 0 is given by $\bar{y}^{\mathsf{T}}B'(0)\bar{x} = \bar{y}^{\mathsf{T}}\left(\frac{1}{2}\sum_{1\leq i< j\leq N}\alpha_{j}\alpha_{i}[A_{j}, A_{i}]\right)\bar{x}$. This, together with Lemma 1 and Eq. (24), proves (9).

6.3 Slow Markovian Switching

In this section, devoted to the proof of (10), σ is a Markov chain as in Sect. 2.2. We use the notations of Sect. 2.2. In view of (7), the goal is now to give an expansion of μ_{ω} when ω vanishes.

In the following, for $i \in [\![1, N]\!]$, we denote by $(\varphi_t^i)_{t \ge 0}$ the flow on Δ associated to F_i ; namely, for $z \in \Delta$, $\theta_i(t) := \varphi_t^i(z)$ solves $\theta_i'(t) = F_i(\theta_i(t))$ for all $t \ge 0$ with $\theta_i(0) = z$. Recall that x_i stands for a unit right eigenvector of A_i . The following follows e.g. from (Benaïm and Strickler 2019, Lemma 6).

Lemma 3 Assuming that A_1, \ldots, A_N are Metzler and irreducible, there exist C, a > 0 such that for all $z \in \Delta$, $i \in [1, N]$ and $t \ge 0$,

$$|\varphi_t^i(z) - x_i| \leqslant C e^{-at}.$$
(25)

In the slow switching regime, since the signal $\sigma(\omega t)$ stays constant for very long times, Lemma 3 shows that the process θ in (5) spends most of its time close to the points $(x_i)_{i \in [1,N]}$, and μ_{ω} is then expected to be close to

$$\tilde{\mu}_0 = \sum_{i=1}^N \alpha_i \delta_{x_i,i}.$$

The next statement provides the first order expansion of this convergence. Notice that its proof doesn't rely on the specific form of the vector fields (6), but only on the contraction established in Lemma 3 (so that the next result can be straighforwardly extended to slow swithching between any contracting flows—i.e. assuming (25)—over a compact manifold)

Proposition 4 Assuming that A_1, \ldots, A_N are Metzler and irreducible, for all $f \in C^1(\Delta \times [\![1, N]\!])$,

$$\mu_{\omega}f = \tilde{\mu}_0 f + \omega \tilde{c}_1 + \mathop{o}_{\omega \to 0}(\omega)$$

with

$$\tilde{c}_1 = \sum_{i,j=1}^N \alpha_i q_{ij} \int_0^\infty \left(f\left(\varphi_s^j(x_i), j\right) - f(x_j, j) \right) ds.$$

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Proof Fix $f \in C^1(\Delta \times [[1, N]])$. Denote by $(T_k)_{k \in \mathbb{N}}$ the jump times of the Markov chain $(\sigma(\omega t))_{t \ge 0}$ and by ν_{ω} the invariant measure of the discrete-time chain $(\theta(T_k), \sigma(\omega T_k))_{k \in \mathbb{N}}$, called the skeleton chain associated to $(\theta(t), \sigma(\omega t))_{t \ge 0}$. Recall the following relation between ν_{ω} and μ_{ω} (see (Davis 1993, Theorem 34.31 p.123)):

$$\mu_{\omega}f = \int_{\Delta \times [\![1,N]\!]} \int_0^\infty f\left(\varphi_s^i(z), i\right) \omega e^{-\omega s} \mathrm{d}s \nu_{\omega}(\mathrm{d}z\mathrm{d}i).$$
(26)

Thanks to Lemma 3, for any $(z, i) \in \Delta \times [[1, N]]$ we can write

$$\int_{0}^{\infty} f\left(\varphi_{s}^{i}(z), i\right) \omega e^{-\omega s} \mathrm{d}s$$

$$= f(x_{i}, i) + \omega \int_{0}^{\infty} \left(f\left(\varphi_{s}^{i}(z), i\right) - f(x_{i}, i) \right) e^{-\omega s} \mathrm{d}s$$

$$= f(x_{i}, i) + \omega \int_{0}^{\infty} \left(f\left(\varphi_{s}^{i}(z), i\right) - f(x_{i}, i) \right) \mathrm{d}s + \underset{\omega \to 0}{o}(\omega), \quad (27)$$

by dominated convergence. On the other hand, since v_{ω} is invariant for the Markov kernel T given by

$$\mathcal{T}f(z,i) = \sum_{j=1}^{N} q_{ij} \int_0^\infty f\left(\varphi_s^i(z), j\right) \omega e^{-\omega s} \mathrm{d}s,$$

using that $v_{\omega} = v_{\omega} \mathcal{T}$, that the marginal on $[\![1, N]\!]$ of v_{ω} is α and that, thanks to Lemma 3,

$$\left|\mathcal{T}f(x,i) - \sum_{j=1}^{N} q_{ij} f(x_i,j)\right| \leq C \|\nabla_x f\|_{\infty} \omega$$

for some C > 0 independent from ω , we immediately get

$$\nu_{\omega} f \xrightarrow[\omega \to 0]{} \sum_{i,j=1}^{N} \alpha_i q_{ij} f(x_i, j).$$

Using this after (27) (and, again, that the marginal of v_{ω} on $[\![1, N]\!]$ is α) in (26) we end up with

$$\begin{split} \mu_{\omega}f &= \tilde{\mu}_{0}f + \omega \int_{\Delta \times [\![1,N]\!]} \int_{0}^{\infty} \left(f\left(\varphi_{s}^{j}(z),i\right) - f(x_{j},j) \right) \mathrm{d}s v_{\omega}(\mathrm{d}z\mathrm{d}i) + \underset{\omega \to 0}{o}(\omega) \\ &= \tilde{\mu}_{0}f + \omega \sum_{i,j=1}^{N} \alpha_{i}q_{ij} \int_{0}^{\infty} \left(f\left(\varphi_{s}^{j}(x_{i}),j\right) - f(x_{j},j) \right) \mathrm{d}s + \underset{\omega \to 0}{o}(\omega). \end{split}$$

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This concludes the proof.

In view of (7) and Proposition 4, the proof of the expansion (10) in the slow Markovian switching case is concluded by the following.

Lemma 4 In Proposition 4, for $f(z, i) = 1 \cdot A_i z$, we have

$$\tilde{c}_1 = \sum_{i,j=1}^N \alpha_i q_{ij} \ln(y_j^\mathsf{T} x_i).$$

Proof Notice that, for all $z \in \Delta_d$,

$$f\left(\varphi_s^j(z), j\right) = \frac{\mathbb{1}_d^{\mathsf{T}} A_j e^{sA_j} z}{\mathbb{1}_d^{\mathsf{T}} e^{sA_j} z} = \frac{d}{ds} \ln(\mathbb{1}_d^{\mathsf{T}} e^{sA_j} z).$$

Theorefore, using that $x_j = \varphi_s^j(x_j)$, one has

$$\int_0^\infty \left(f\left(\varphi_s^j(x_i), j\right) - f(x_j, j) \right) \mathrm{d}s = \int_0^\infty \frac{d}{ds} \left(\ln\left(\frac{\mathbbm{1}_d^\mathsf{T} e^{sA_j} x_i}{\mathbbm{1}_d^\mathsf{T} e^{sA_j} x_j}\right) \right) \mathrm{d}s$$
$$= \lim_{s \to \infty} \ln\left(\frac{\mathbbm{1}_d^\mathsf{T} e^{sA_j} x_i}{\mathbbm{1}_d^\mathsf{T} e^{sA_j} x_j}\right)$$
$$= \ln(y_j^\mathsf{T} x_i),$$

where we have used (once again) Perron-Frobenius Theorem.

7 Proof of Theorem 3

We first prove a more general result about random switching of Metzler matrices that are symmetric. This result applies to the special case of (21) when the dispersal matrix *L* is symmetric.

Proposition 5 In the settings of Theorem 1, assume that all the matrices A_1, \ldots, A_N are symmetric. Then, in (8) and (10), $c_{sp} \leq 0$ and $c_{sM} \leq 0$. Moreover, either all the x_i are equal, in which case $\omega \mapsto \Lambda_p(\omega)$ and $\omega \mapsto \Lambda_M(\omega)$ are constant, or otherwise $c_{sp} < 0$ and $c_{sM} < 0$.

Proof We only give the proof for the Markov case, since in the slow switching regime, c_{sp} is positively proportional to c_{sM} for a particular Markov chain, as described at the end of Sect. 3.1. Since A_i is symmetric, its left eigenvector y_i is proportional the right eigenvector x_i . Moreover, due to the normalization condition $y_i^T x_i = 1$, we have $y_i = ||x_i||^{-2} x_i$. Therefore,

$$\prod_{i,j} \left(y_j^{\mathsf{T}} x_i \right)^{q_{i,j}\alpha_i} = \prod_{i,j} \left(\|x_j\|^{-2} x_j^{\mathsf{T}} x_i \right)^{q_{i,j}\alpha_i}$$
$$\leq \prod_{i,j} \left(\frac{\|x_i\|}{\|x_j\|} \right)^{q_{i,j}\alpha_i},$$

where the last line follows from Cauchy–Schwarz inequality. Now, in this last product, the exponent of each $||x_i||$ is $\sum_j \alpha_i q_{i,j} - \sum_j \alpha_j q_{j,i}$, which is zero since α is invariant for Q. This entails that $c_{sM} \leq 0$. Moreover, $c_{sM} = 0$ if and only if there is equality in all the Cauchy–Schwarz inequalities we used, namely, if and only if all the x_i are positively correlated, and thus, equal. In that case, one easily checks that μ_{ω} , the invariant probability measure of the PDMP on the sphere considered in Sect. 6.3 for the proof of (10), is $\delta_{x_1} \otimes \alpha$ for all values of ω . In view of (7), $\omega \mapsto \Lambda_M(\omega)$ is thus constant. In the periodic case, $\Lambda_p(\omega)$ can also be written as the integral of a function of the unique globally asymptotically periodic solution of the system on the sphere (see Formula 29 in Theorem 8 in Benaim et al. (2024)). Here again, it is easy to check that the constant solution equal to x_1 is the unique periodic solution, and thus $\Lambda_p(\omega)$ is constant.

The next two propositions provide show that $c_{fM} > c_{fp} = 0$ in the fast-switching limit.

Proposition 6 In the case (21), $c_{fp} = 0$.

Proof Recall that

$$c_{fp} = \frac{1}{2} \sum_{i < j} \alpha_i \alpha_j \bar{y}^{\mathsf{T}} [A_j, A_i] \bar{x}.$$

Since $A_i = R_i + L$ and R_i and R_j commute, we end up with $[A_j, A_i] = [L, R_i] + [R_j, L]$. Now,

$$\begin{split} \bar{y}^{\mathsf{T}}[L, R_i] \bar{x} &= \bar{y}^{\mathsf{T}} L R_i \bar{x} - \bar{y}^{\mathsf{T}} R_i L \bar{x} \\ &= \bar{y}^{\mathsf{T}} (\lambda(\bar{A}) - \bar{R}) R_i \bar{x} - \bar{y}^{\mathsf{T}} R_i (\lambda(\bar{A}) - \bar{R}) \bar{x} \\ &= 0, \end{split}$$

where we have used that \overline{R} and R_i commute and that by definition,

$$\bar{y}^{\mathsf{T}}(\bar{R}+L) = \lambda(\bar{A})\bar{y}^{\mathsf{T}}, \quad (\bar{R}+L)\bar{x} = \lambda(\bar{A})\bar{x}$$

Proposition 7 In the case (21), $c_{fM} > 0$.

Proof First, let us prove that, in the case (21),

$$c_{fM} = \sum_{i,j} \alpha_i (Q - I)_{i,j}^{-1} \left(\bar{y}^{\mathsf{T}} R_j \bar{x} \bar{y}^{\mathsf{T}} R_i \bar{x} - \bar{y}^{\mathsf{T}} R_j R_i \bar{x} \right).$$
(28)

Indeed,

$$\bar{y}^{\mathsf{T}}A_j\bar{x}\bar{y}^{\mathsf{T}}A_i\bar{x} - \bar{y}^{\mathsf{T}}A_jA_i\bar{x} = \bar{y}^{\mathsf{T}}R_j\bar{x}\bar{y}^{\mathsf{T}}R_i\bar{x} - \bar{y}^{\mathsf{T}}R_jR_i\bar{x} + B_i + C_j + D,$$

where

$$B_i = \bar{y}^{\mathsf{T}} L \bar{x} \bar{y}^{\mathsf{T}} R_i \bar{x} - \bar{y}^{\mathsf{T}} L R_i \bar{x}$$

$$C_j = \bar{y}^{\mathsf{T}} R_j \bar{x} \bar{y}^{\mathsf{T}} L \bar{x} - \bar{y}^{\mathsf{T}} R_j L \bar{x}$$

$$D = \bar{y}^{\mathsf{T}} L \bar{x} \bar{y}^{\mathsf{T}} L \bar{x} - \bar{y}^{\mathsf{T}} L^2 \bar{x}.$$

Using that $\sum_{i} \alpha_{i} (Q - I)_{ij}^{-1} = 0 = \sum_{j} (Q - I)_{i,j}^{-1}$, we end up with $\sum_{i,j} \alpha_{i} (Q - I)_{i,j}^{-1} (B_{i} + C_{j} + L) = 0$, leading to (28).

For $k \in [\![1, N]\!]$, write $a_k = \bar{x}_k \bar{y}_k$ and $(R_i)_{k,k} = r^{i,k}$. Since the R_i 's are diagonal, we get that $\bar{y}^{\mathsf{T}} R_i \bar{x} = \sum_k a_k r^{i,k}$. Now, let $X = (X_1, \ldots, X_N)$ be a random variable taking the value $(r^{1,k}, \ldots, r^{N,k})$ with probability a_k for all $k \in [\![1, N]\!]$ and define $\varphi : \mathbb{R}^N \to \mathbb{R}$ by

$$\varphi:(x_1,\ldots,x_N)\mapsto -\sum_{i,j}\alpha_i(Q-I)_{i,j}^{-1}x_ix_j.$$

It is readily checked that

$$\sum_{i,j} \alpha_i (Q - I)_{i,j}^{-1} \left(\bar{y}^{\mathsf{T}} R_j \bar{x} \bar{y}^{\mathsf{T}} R_i \bar{x} - \bar{y}^{\mathsf{T}} R_j R_i \bar{x} \right) = \mathbb{E}(\varphi(X)) - \varphi(\mathbb{E}(X)).$$

It remains to prove that φ is convex, which will imply by Jensen inequality that $c_{fM} > 0$. Since φ is a quadratic form, it is convex if and only if it is positive. Yet, $\varphi(x) = -\int f(i)(Q-I)^{-1}f(i)\alpha(di)$, where $f(i) = x_i$, which can be interpreted as an asymptotic variance, and is thus positive (see the discussion after Proposition 4 in Monmarché and Strickler (2023)).

Finally, we consider the case of d = 2 patches. The matrices A_i in case (21) can be written as

$$A_i = \begin{pmatrix} a_i & \alpha \\ \beta & b_i \end{pmatrix}, \quad i = 1, \dots, N.$$

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for some $a_i, b_i \in \mathbb{R}$ and $\alpha, \beta > 0$ (recall that the matrices are Metzler and irreducible). The right and left eigenvectors can be computed explicitly as follows

$$x_i = \frac{1}{2\alpha + g_i} [2\alpha, g_i]^{\mathsf{T}}, \quad y_i = \frac{2\alpha + g_i}{4\alpha\beta + g_i^2} [2\beta, g_i]^{\mathsf{T}},$$
 (29)

with

$$g_i = \sqrt{(b_i - a_i)^2 + 4\alpha\beta} + b_i - a_i > 0.$$

Note that for $i \neq j$, $g_i = g_j$ if and only if $x_i = x_j$, if and only if $A_i = A_j + \delta_i I$ for some $\delta_i \in \mathbb{R}$.

Proposition 8 In case (21), when d = 2,

$$c_{sM} = \sum_{i,j} \alpha_i q_{ij} \ln \left(\frac{4\alpha\beta + g_i g_j}{4\alpha\beta + g_j^2} \right) \le 0.$$

Moreover, either for all j > 1, there is δ_j such that $A_j = A_1 + \delta_j I$ and $\omega \mapsto \Lambda_M(\omega)$ is constant and in particular, $c_{sM} = 0$; or otherwise $c_{sM} < 0$.

Proof By Eqs. (10) and (29), we get that

$$c_{sM} = \sum_{i,j} \alpha_i q_{ij} \ln \left(\frac{4\alpha\beta + g_i g_j}{4\alpha\beta + g_j^2} \frac{2\alpha + g_j}{2\alpha + g_i} \right).$$

Note that by invariance of α with respect to Q, we have for all $(\eta_i)_{1 \le i \le N}$

$$\sum_{i,j} \alpha_i q_{i,j} \eta_i = \sum_{i,j} \alpha_i q_{i,j} \eta_j = \sum_i \alpha_i \eta_i$$
(30)

This yields

$$c_{sM} = \sum_{i,j} \alpha_i q_{ij} \ln\left(\frac{4lphaeta + g_i g_j}{4lphaeta + g_j^2}
ight).$$

Now, applying for all *i* and *j* Cauchy–Schwarz inequality to the two-dimensional vectors $(\sqrt{4\alpha\beta}, g_i)$ and $(\sqrt{4\alpha\beta}, g_j)$, we have

$$(4\alpha\beta + g_ig_j) \leq (4\alpha\beta + g_i^2)^{1/2} (4\alpha\beta + g_j^2)^{1/2},$$

with equality if and only if $g_i = g_j$. Therefore,

$$\sum_{i,j} \alpha_i q_{ij} \ln\left(4\alpha\beta + g_i g_j\right) \le \sum_{i,j} \alpha_i q_{ij} \ln\left(\left(4\alpha\beta + g_i^2\right)^{1/2} \left(4\alpha\beta + g_j^2\right)^{1/2}\right)$$

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$$= \frac{1}{2} \sum_{i,j} \alpha_i q_{ij} \ln\left(4\alpha\beta + g_i^2\right) + \frac{1}{2} \sum_{i,j} \alpha_i q_{ij} \ln\left(4\alpha\beta + g_j^2\right)$$
$$= \sum_{i,j} \alpha_i q_{ij} \ln\left(4\alpha\beta + g_i^2\right),$$

where the last equality comes from (30), and the first inequality is an equality if and only if $g_i = g_j$ for all *i* and *j*. Hence, we get that $c_{sM} \le 0$, and $c_{sM} < 0$ except if all the g_i are equal, that is, if and only if all the x_i are equal. But, as explained in the proof of Proposition 5, this implies that the map $\omega \mapsto \Lambda_M(\omega)$ is constant. \Box

8 Proof of Proposition 3

Because of the symmetries of the problem, the principal right eigenvector x_i of $A_i = L + R_i$ is simply x_1 up to a circular relabelling of the states, i.e. $x_{i,k} = x_{1,k-i+1}$ for all $k \in [\![1,d]\!]$ (recall that indexes are understood modulo d). Similarly, denoting by \hat{y}_i the principal left eigenvector of A_i normalized so that $\mathbb{1}_d^T \hat{y}_i = 1$ (so that $y_i = (x_i^T \hat{y}_i)^{-1} \hat{y}_i$), which is the right eigenvector of $R_i + L^T$ (similar to $R_i + L$ except that migration turns in the other direction), it is obtained from x_i by $\hat{y}_{i,k} = x_{i,2i-k}$. Then, in (10), in the synchronized case,

$$c_{sM} = c_{sM}^{sync} := \frac{1}{d} \sum_{i=1}^{d} \ln(y_{i+1}^{\mathsf{T}} x_i) = \ln(y_2^{\mathsf{T}} x_1) = \ln(\hat{y}_2^{\mathsf{T}} x_1) - \ln(\hat{y}_1^{\mathsf{T}} x_1),$$

while, in the a-synchronized case,

$$c_{sM} = c_{sM}^{async} := \frac{1}{d} \sum_{i=1}^{d} \ln(y_{i-1}^{\mathsf{T}} x_i) = \ln(\hat{y}_d^{\mathsf{T}} x_1) - \ln(\hat{y}_1^{\mathsf{T}} x_1),$$

Denoting for brevity $\lambda = \lambda(A_1), x_1$ solves

$$(\beta - 1)x_{1,1} + x_{1,d} = \lambda x_{1,1}, \qquad -x_{1,i} + x_{1,i-1} = \lambda x_{1,i} \quad \forall i \in [\![1,d]\!],$$

which, writing $r = \lambda + 1$, is solved as

$$x_{1,i} = (r - \beta)r^{d-i}x_{1,1} \quad \forall i \in [\![2,d]\!]$$

with $x_{1,1}$ being fixed by the normalization. Moreover, the equation $x_{1,1} = rx_{1,2}$ shows that *r* is the unique positive solution of

$$(r - \beta)r^{d-1} = 1 \tag{31}$$

In particular, $r > \beta$ and $\lambda = r - 1$ is always larger than -1, and has the same sign as β (since the solution for $\beta = 0$ is r = 1, and the solution of this equation is an increasing function of β).

Using the symmetries previously mentioned,

$$\hat{y}_{2}^{\mathsf{T}} x_{1} = (r-\beta)^{2} x_{1,1}^{2} \begin{pmatrix} r^{d-2} \\ r^{d-1} \\ 1 \\ \vdots \\ r^{d-4} \\ r^{d-3} \end{pmatrix} \cdot \begin{pmatrix} r^{d-1} \\ r^{d-2} \\ r^{d-3} \\ \vdots \\ r \\ 1 \end{pmatrix} = (r-\beta)^{2} x_{1,1}^{2} \left[(d-2)r^{d-3} + 2r^{2d-3} \right]$$
$$= x_{1,1}^{2} \left[(d-2)(r-\beta)r^{-2} + 2r^{-1} \right],$$

while

$$\hat{y}_{1}^{\mathsf{T}} x_{1} = (r-\beta)^{2} x_{1,1}^{2} \begin{pmatrix} r^{d-1} \\ 1 \\ r \\ \vdots \\ r^{d-3} \\ r^{d-2} \end{pmatrix} \cdot \begin{pmatrix} r^{d-1} \\ r^{d-2} \\ r^{d-3} \\ \vdots \\ r \\ 1 \end{pmatrix} = (r-\beta)^{2} x_{1,1}^{2} \left[(d-1)r^{d-2} + r^{2d-2} \right]$$
$$= x_{1,1}^{2} \left[(d-1)(r-\beta)r^{-1} + 1 \right],$$

and

$$\hat{y}_{d}^{\mathsf{T}}x_{1} = (r-\beta)^{2}x_{1,1}^{2} \begin{pmatrix} 1\\r\\r^{2}\\\vdots\\r^{d-2}\\r^{d-1} \end{pmatrix} \cdot \begin{pmatrix} r^{d-1}\\r^{d-2}\\r^{d-3}\\\vdots\\r\\1 \end{pmatrix} = (r-\beta)^{2}x_{1,1}^{2}dr^{d-1}$$
$$= x_{1,1}^{2}(r-\beta)d.$$

We have thus obtained that

$$c_{sM}^{sync} = \ln\left(\frac{\hat{y}_2^{\mathsf{T}} x_1}{\hat{y}_1^{\mathsf{T}} x_1}\right) = \ln\left(\frac{(d-2)(r-\beta)+2r}{(d-1)(r-\beta)r+r^2}\right)$$
$$= \ln\left(\frac{(d-2)r^{1-d}+2r}{(d-1)r^{2-d}+r^2}\right)$$
$$= \ln\left(\frac{(d-2)+2r^d}{(d-1)r+r^{d+1}}\right).$$

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This has the same sign as f(r) where

$$f(s) = (d-2) + 2s^d - (d-1)s - s^{d+1}.$$

When d = 3, we see that

$$f(s) = -s^4 + 2s^3 - 2s + 1 = (1 - s)^3(1 + s),$$

which for s > 0 has the same sign as 1 - s. As we saw, $1 - r = -\lambda$ has the same sign as $-\beta$, and as a conclusion in the case d = 3, the sign of c_{sM} is the opposite of the sign of β .

Consider the case d > 3 (for d = 2, L is symmetric). Computing

$$f'(s) = 2ds^{d-1} - (d-1) - (d+1)s^d$$

$$f''(s) = 2d(d-1)s^{d-2} - d(d+1)s^{d-1},$$

we see that f(1) = f'(1) = 0, and f'' cancels exactly twice, at 0 and $s_* = \frac{2(d-1)}{d+1} \in (1, 2)$, and is positive on $(0, s^*)$ and negative on $(s^*, +\infty)$. In particular, f is convex decreasing positive over (0, 1), increasing convex over $(1, s_*)$ and then it becomes strictly concave, being eventually decreasing and then going to $-\infty$. In particular, it admits exactly one root r^* over $(1, \infty)$, with $r_* > s_*$, f(s) > 0 if $s \in (1, r_*)$ and f(s) < 0 if $s > r_*$. Since the solution r_β of (31) is an increasing function of β and goes to infinity as β goes to infinity, we obtain that, for each d, there is a unique $\beta_d > 0$ such that $r_\beta = r_*$ (which is simply $\beta = r_* - r_*^{1-d}$). For $\beta < \beta_d$ (resp. >), $r_\beta < r_*$ (resp. >), hence $f(r_\beta) > 0$ (resp. <), so that $c_{sM} > 0$ (resp. < 0).

In the asynchronised case,

$$c_{sM}^{async} = \ln\left(\frac{\hat{y}_2^{\mathsf{T}} x_1}{\hat{y}_1^{\mathsf{T}} x_1}\right) = \ln\left(\frac{(r-\beta)dr}{(d-1)(r-\beta)+r}\right)$$
$$= \ln\left(\frac{dr^{2-d}}{(d-1)r^{1-d}+r}\right) = \ln\left(\frac{dr}{d-1+r^d}\right)$$

This has the same sign as f(r) with $f(s) = -s^d + ds - (d-1)$. Since $f'(s) = d(1 - s^{d-1})$, f is increasing over [0, 1] and decreasing over $[1, +\infty)$, reaching its global maximum at 1, with f(1) = 0. In particular, for $\beta \neq 0$, $r \neq 1$ and thus f(r) < 0 from which $c_{sM}^{async} < 0$.

The periodic case follows from the discussion at the end of Sect. 3.1

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